Торіс		Ref	Ex
Matrices and Transformations	<ul> <li>Introduction to Matrices</li> <li>Add, subtract and multiply conformable matrices.</li> <li>Multiply a matrix by a scalar.</li> <li>Understand and use zero and identity matrices.</li> </ul>	P3.1 P3.2	
	<ul> <li>Matrices and Transformations</li> <li>Find the 2x2 matrix associated with a linear transformation and vice versa. <ul> <li>Reflection in coordinate axes and lines y = ± x</li> <li>Rotation through any angle about (0, 0)</li> <li>Stretches parallel to the x-axis and y-axis</li> <li>Enlargement about centre (0, 0), with scale factor k, (k ≠ 0).</li> </ul> </li> <li>Successive transformations – A followed by B is represented by the matrix BA.</li> <li>Find 3x3 matrices representing 3D transformations <ul> <li>Reflection in plane x=0, y=0 or z=0</li> <li>Rotations through multiples of 90° about the x, y or z axes.</li> </ul> </li> </ul>	P3.3	
	<ul> <li>Invariant Points</li> <li>Find co-ordinates of invariant points for a given transformation</li> <li>Find equations of invariant lines for a given transformation</li> </ul>	P3.4	
	Matrices and Transformations Assessment	I	
Complex Numbers	<ul> <li>Introduction to Complex Numbers</li> <li>Understand the definition of a complex number</li> <li>Understand and use the terms real part and imaginary part.</li> <li>Add, subtract, multiply and divide complex numbers in the form <i>x+iy</i> with <i>x</i> and <i>y</i> real</li> <li>Find the complex conjugate</li> <li>Solve any quadratic equation with real coefficients.</li> <li>Know that the non-real roots of quadratic equations (with real coefficients) form a conjugate pair</li> <li>Find the square root of a complex number</li> </ul>	P2.1 P2.2 P2.3	
	<ul> <li>Use and interpret Argand diagrams.</li> <li>Represent the sum or difference of two complex numbers on an Argand diagram.</li> <li>Complex Numbers Assessment</li> </ul>		

Topic		Ref	Ex	
Matrices and their Inverses	<ul> <li>2x2 Matrices</li> <li>Calculate the determinant of a 2x2 matrix</li> <li>Use the property det AB = det A x det B</li> <li>Know that the magnitude of the determinant of a 2x2 matrix gives the area scale factor of the associated transformation, and that the sign of the determinant indicates whether the orientation of the image is preserved or reversed.</li> <li>Understand what is meant by a singular matrix and a non-singular matrix</li> <li>Calculate the inverse of a 2x2 matrix</li> <li>Prove and use the property (AB) <sup>-1</sup> = B <sup>-1</sup> A <sup>-1</sup></li> </ul>	P3.5 P3.6		
	<ul> <li>3x3 Matrices</li> <li>Calculate the determinant of a 3x3 matrix either manually or using the matrix facility on a calculator.</li> <li>Know that the magnitude of the determinant of a 3x3 matrix gives the volume scale factor of the associated transformation, and that the sign of the determinant indicates whether the orientation of the image is preserved or reversed.</li> <li>Calculate the inverse of a 3x3 matrix either manually or using the matrix facility on a calculator.</li> </ul>	P3.5 P3.6 P3.7		
	<ul> <li>Matrices and Simultaneous Equations</li> <li>Solve three linear simultaneous equations in three variables by use of the inverse matrix</li> <li>Interpret geometrically the solution and failure of solution of three simultaneous linear equations. <ul> <li>meet in a point</li> <li>form a sheaf</li> <li>form a prism or are otherwise inconsistent</li> </ul> </li> </ul>	P3.7 P3.8		
	Matrices and their Inverses Assessment			
Roots of polynomials	<ul> <li>Roots and coefficients</li> <li>Know about the relationships between roots and coefficients of quadratic, cubic and quartic equations.</li> <li>Be able to form a new equation whose roots are related to the roots of a given equation by a linear transformation.</li> </ul>	P4.1 P4.2		
	<ul> <li>Complex Roots of Polynomials</li> <li>Understand that non-real roots of polynomial equations with real coefficients occur in conjugate pairs.</li> <li>Be able to solve cubic or quartic equations with real coefficients.</li> </ul>	P2.1		
Roots of Polynomials Assessment				

Торіс		Ref	Ex
Complex Numbers and Geometry	<ul> <li>Modulus and Argument</li> <li>Find the modulus and argument of a complex number</li> <li>Convert between the Cartesian form and the modulus- argument form of a complex number.</li> <li>Multiply and divide complex numbers in modulus- argument form</li> </ul>	P2.5 P2.6	
	<ul> <li>Loci in the complex plane</li> <li>To construct and interpret simple loci in the Argand diagram. <ul> <li> z-a =r</li> <li>Arg (z - a) = β</li> <li> z-a = z-b </li> </ul> </li> <li>Understand and use Radians as an alternative angle measure.</li> </ul>	P2.7	
	Complex Numbers and Geometry Assessment	1	
Sequences, Series and Proof	<ul> <li>Summing Series</li> <li>Understand and use formulae for the sums of integers, squares and cubes and use these to sum other series.</li> </ul>	P4.3	
	<ul> <li>Proof by Induction</li> <li>Construct proofs using mathematical induction.</li> <li>Contexts include sums of series, divisibility and powers of matrices.</li> </ul>	P1.1	
	Sequences and Series Assessment	,	
Vectors and 3-D Space	<ul> <li>The Scalar Product</li> <li>Calculate the scalar product of two vectors</li> <li>Use the scalar product to find the angle between two vectors</li> <li>Check whether two vectors are perpendicular using the scalar product.</li> </ul>	P6.3 P6.4	
	<ul> <li>The Equation of a Line</li> <li>Express the equation of a line in three dimensions in vector form and in Cartesian form</li> <li>Calculate the angle between two lines using the scalar product</li> <li>Find the point of intersection of two straight lines given in vector form</li> <li>Understand that two lines in three dimensions may either intersect, be parallel or be skew</li> </ul>	P6.1	
	<ul> <li>The Equation of a Plane</li> <li>Form and use vector and Cartesian equations of a plane</li> <li>Convert between the different forms for the equation of a plane</li> <li>Understand that a vector which is perpendicular to a plane is perpendicular to any vector in the plane</li> <li>Find the angle between two planes by finding the angle between their normals</li> <li>Find the angle between a line and a plane</li> <li>Find the point of intersection of a line and a plane</li> </ul>	P6.2 P6.3 P6.5	

Торіс		Ref	Ex
Vectors and 3-D Space (cont.)	<ul> <li>Finding Distances</li> <li>Find the perpendicular distance from a point to a plane</li> <li>Find the perpendicular distance from a point to a line</li> <li>Find the perpendicular distance between two lines</li> </ul>	P6.5	
Vectors and 3-D Space Assessment			
Further Calculus	<ul> <li>Volumes of Revolution</li> <li>Calculate the volume of a solid of revolution formed by rotating a plane region about the x-axis or y-axis.</li> <li>Derive the formulae for calculating the volume of revolution.</li> </ul>	P5.1	
Further Calculus Assessment			